

## 1. Conditional Probability

In many scenarios, the occurrence of one event affects the likelihood of another. **Conditional probability** is the probability of an event  $E$  occurring, given that another event  $F$  has already occurred.  $E$  occurring, given that another event  $F$  has already occurred.

### A. Intuitive Understanding: The Reduced Sample Space

When we know event  $F$  has occurred, any outcomes in the original sample space  $S$  that are not in  $F$  are no longer possible. This information effectively **reduces the sample space** from  $S$  to the subset  $F$ . The only outcomes of  $E$  that remain relevant are those that are also in  $F$ , which is the intersection  $E \cap F$ .  $F$  has occurred, any outcomes in the original sample space  $S$  that are not in  $F$  are no longer possible. This information effectively reduces the sample space from  $S$  to the subset  $F$ . The only outcomes of  $E$  that remain relevant are those that are also in  $F$ , which is the intersection  $E \cap F$ .

### B. Formal Definition

For two events  $E$  and  $F$  associated with the same sample space, where  $P(F) \neq 0$ , the conditional probability is defined as:  $E$  and  $F$  associated with the same sample space, where  $P(F) \neq 0$ , the conditional probability is defined as:

$$P(E|F) = \frac{P(E \cap F)}{P(F)}$$

### C. Properties of Conditional Probability

- Property 1:** The probability of the sample space  $S$  given an event  $F$  is 1, and the probability of  $F$  given  $F$  is also 1.  $S$  given an event  $F$  is 1, and the probability of  $F$  given  $F$  is also 1.  $P(S|F) = P(F|F) = 1$
- Property 2:** If  $A$  and  $B$  are any two events and  $F$  is a conditioning event, the probability of their union is:  $A$  and  $B$  are any two events and  $F$  is a conditioning event, the probability

of their union is:  
 $P((A \cup B)|F) = P(A|F) + P(B|F) - P((A \cap B)|F)$

**Note:** If  $A$  and  $B$  are **disjoint (mutually exclusive)**, then  $P((A \cap B)|F) = 0$ .  $A$  and  $B$  are disjoint (mutually exclusive), then  $P((A \cap B)|F) = 0$ .

- Property 3:** The probability of the complement of an event  $E$  given  $F$  is:  $E$  given  $F$  is:  $P(E'|F) = 1 - P(E|F)$

## 2. Multiplication Theorem on Probability

The **multiplication theorem** allows us to find the probability of the **simultaneous occurrence** of two or more events, denoted by  $E \cap F$  or simply  $EF$ .  $E \cap F$  or simply  $EF$ .

### A. Derivation for Two Events

From the definition of conditional probability, we can derive the multiplication rule:  
 $P(E \cap F) = P(E) \cdot P(F|E), \quad P(E) \neq 0$

Alternatively:

$$P(E \cap F) = P(F) \cdot P(E|F), \quad P(F) \neq 0$$

### B. Extension to Multiple Events

The rule can be extended to three or more events by applying it sequentially:  
 $P(E \cap F \cap G) = P(E) \cdot P(F|E) \cdot P(G|E \cap F)$  In this notation,  $P(G|E \cap F)$  is the probability that  $G$  occurs given that both  $E$  and  $F$  have already occurred.  $P(G|E \cap F)$  is the probability that  $G$  occurs given that both  $E$  and  $F$  have already occurred.

## 3. Independent Events

Two events are **independent** if the occurrence of one does not affect the probability of the occurrence of the other.

### A. Formal Definition

Events  $E$  and  $F$  are independent if:  $E$  and  $F$  are independent if:

- $P(E|F) = P(E)P(E|F) = P(E)$
- $P(F|E) = P(F)P(F|E) = P(F)$

Using the multiplication theorem, this leads to the **product rule for independence**:  
 $P(E \cap F) = P(E) \cdot P(F)$

### B. Independent vs. Mutually Exclusive

It is a common mistake to confuse these terms.

- **Mutually Exclusive:** Events cannot happen at the same time (no outcomes in common).
- **Independent:** The probability of one does not change the probability of the other.
- **Crucial Difference:** Two independent events with non-zero probabilities **cannot** be mutually exclusive, as they must be able to occur together to satisfy the product rule.

- $P(A \cap B) = P(A)P(B)$   
 $P(A \cap B) = P(A)P(B)$
- $P(A \cap C) = P(A)P(C)$   
 $P(A \cap C) = P(A)P(C)$
- $P(B \cap C) = P(B)P(C)$   
 $P(B \cap C) = P(B)P(C)$
- $P(A \cap B \cap C) = P(A)P(B)P(C)$  If even one of these conditions fails, the events are not mutually independent.  
 $P(A \cap B \cap C) = P(A)P(B)P(C)$  If even one of these conditions fails, the events are not mutually independent.

### 4. Total Probability

Before calculating "reverse" probabilities, we must understand how to calculate the total probability of an event that can happen under different scenarios.

#### A. Partition of a Sample Space

A set of events  $E_1, E_2, \dots, E_n$  is a **partition** of sample space  $S$  if:  $E_1, E_2, \dots, E_n$  is a partition of sample space  $S$  if:

- They are pairwise disjoint ( $E_i \cap E_j = \phi$ ).
- They are exhaustive ( $E_1 \cup E_2 \cup \dots \cup E_n = S$ ).
- Each has a non-zero probability ( $P(E_i) > 0$ ).

#### B. Theorem of Total Probability

If  $E_1, E_2, \dots, E_n$  is a partition of  $S$ , then for any event  $A$  associated with  $S$ , the total probability  $P(A)$  is the sum of the probabilities of  $A$  occurring under each partition.  $E_1, E_2, \dots, E_n$  is a partition of  $S$ , then for any event  $A$  associated with  $S$ , the total probability  $P(A)$  is the sum of the probabilities of  $A$  occurring under each partition.

### C. Mutual Independence of Three Events

Three events  $A, B$ , and  $C$  are **mutually independent** if they satisfy four conditions:  
 $A, B$ , and  $C$  are mutually independent if they satisfy four conditions:



$$P(A) = \sum_{j=1}^n P(E_j) \cdot P(A|E_j)$$

This formula works

because  $A$  can be decomposed into disjoint components  $(A \cap E_1), (A \cap E_2), \dots, (A \cap E_n)$ .  $A$  can be decomposed into disjoint components  $(A \cap E_1), (A \cap E_2), \dots, (A \cap E_n)$ .

### 5. Bayes' Theorem

Named after **John Bayes**, this theorem provides a way to find the **reverse probability**: the probability of a specific "cause" (partition event  $E_i$ ) given that the "effect" (event  $A$ ) has already occurred.  $E_i$  given that the "effect" (event  $A$ ) has already occurred.

#### A. The Formula

Let  $E_1, E_2, \dots, E_n$  be a partition of  $S$ , and  $A$  be an event with non-zero probability. The probability of  $E_i$  given  $A$  is:  $E_1, E_2, \dots, E_n$  be a partition of  $S$ , and  $A$  be an event with non-zero probability. The probability of  $E_i$  given  $A$  is:

$$P(E_i|A) = \frac{P(E_i) \cdot P(A|E_i)}{\sum_{j=1}^n P(E_j) \cdot P(A|E_j)}$$

#### B. Terminology

- **Hypotheses:** The events  $E_1, E_2, \dots, E_n$  represent the possible causes.  $E_1, E_2, \dots, E_n$  represent the possible causes.
- **Priori Probability:** The initial probability  $P(E_i)$  determined before the experiment.  $P(E_i)$  determined before the experiment.
- **Posteriori Probability:** The updated conditional probability  $P(E_i|A)$  calculated after observing event  $A$ .  $P(E_i|A)$  calculated after observing event  $A$ .

### 6. Summary Table for CUET Preparation

Concept	Key Formula	Context / Usage
<b>Conditional Prob.</b>	$P(E F)$	$P(E F) = \frac{P(E \cap F)}{P(F)}$ $P(E \cap F) = P(E F) \cdot P(F)$
<b>Multiplication Rule</b>	$P(E \cap F) = P(E)P(F)$	Events do not influence each other.
<b>Independence</b>	$P(E \cap F) = P(E)P(F)$	Events do not influence each other.
<b>Total Probability</b>	$P(A) = \sum_{j=1}^n P(E_j)P(A E_j)$	
<b>Bayes' Theorem</b>	$P(E_i A) = \frac{P(E_i)P(A E_i)}{\sum_{j=1}^n P(E_j)P(A E_j)}$	

## 7. Numerical Application Insights (Based on Sources)

- **Tree Diagrams:** Useful for visualizing experiments like tossing a coin and then throwing a die depending on the coin outcome.
- **With/Without Replacement:** In card or ball drawing problems, "without replacement" implies that the events are **dependent**, requiring conditional probability for the second draw.
- **Truth-telling Problems:** Bayes' theorem is often applied to find the probability that a report is actually true (e.g., a man reports a six occurred; what is the probability it actually was a six?).
- **Reliability Tests:** Standard in Bayes' problems involving medical tests (HIV/disease detection) where false positives and false negatives are given.



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